

10/4/17

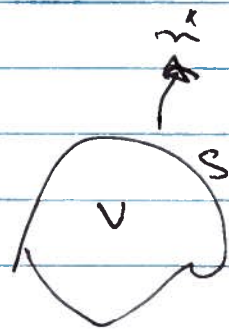
Important

theorems

(11.18)

$$\int_V \vec{\nabla} \cdot \vec{a} \, d^3V = \oint_S \vec{a} \cdot d\vec{S}$$

$$\int_V \vec{\nabla} \cdot \vec{A} \, d^3V = \oint_S \vec{A} \cdot \hat{n} \, d^2S$$



↑ outward,  
↑ closed.

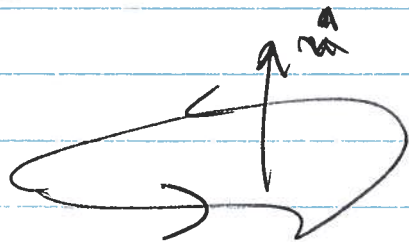
divergence Theorem

(11.23)

$$\int_S (\vec{\nabla} \times \vec{a}) \cdot d\vec{S} = \oint_C \vec{a} \cdot d\vec{r}$$

$$\int_S (\vec{\nabla} \times \vec{A}) \cdot \hat{n} \, d^2S = \oint_C \vec{A} \cdot d\vec{r}$$

↑ closed,



RHR,

②

$$\vec{E} = -\vec{\nabla}V \quad \vec{\nabla} \times \vec{E} \rightarrow 0$$

no curl, only div  $\rightarrow$  "histories"

$$\vec{B} = \vec{\nabla} \times \vec{A} \quad \vec{\nabla} \cdot \vec{B} \rightarrow 0$$

no div only curl  $\rightarrow$  "wraps"

$$\vec{\nabla} \cdot \vec{E} = \vec{\nabla} \cdot (-\vec{\nabla})V = -\vec{\nabla}^2 V = \rho/\epsilon_0$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \vec{\nabla}^2 \vec{A} = \mu_0 \vec{J}$$

Stokes:  $\vec{a} = \nabla \times \vec{c}$        $\vec{c} = \text{vector}$

$$\int_S \vec{\nabla} \times (\nabla \times \vec{c}) \cdot \hat{n} dS = \int_C (\nabla \times \vec{c}) \cdot d\vec{r} = \oint_C \vec{c} \cdot d\vec{r}$$

$$\int_S (\vec{\nabla} \times \vec{c}) \cdot \hat{n} dS = \int_S \vec{c} \cdot (\hat{n} \times \vec{\nabla} \phi) dS$$

$\epsilon_{ijk} \partial_i c_j \hat{n}_k = \epsilon_{ijk} c_i \hat{n}_j \partial_k$

$$\vec{c} \cdot \int_S (\hat{n} \times \vec{\nabla} \phi) dS = \vec{c} \cdot \oint_C \phi d\vec{r}$$

$$\int_S (\hat{n} \times \vec{\nabla} \phi) dS = \oint_C \phi d\vec{r} \quad (11.24)$$

3.

Issue: point Q.

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q\hat{r}}{r^2}$$

Table 10.3

$$\vec{\nabla} \cdot \vec{E} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 E_r) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (\sin\theta \frac{\partial E_\theta}{\partial \theta}) + \frac{1}{r \sin\theta} \frac{\partial E_\phi}{\partial \phi}$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left( \frac{1}{4\pi\epsilon_0} Q \right) = \underline{\underline{0}}$$

But  $\oint_{\text{sphere}(r)} d^2S \hat{n} \cdot \vec{E} = \oint d^2S \cdot \vec{E} = 4\pi r^2 \cdot \left( \frac{Q}{4\pi\epsilon_0 r^2} \right)$

$\frac{Q}{\epsilon_0}$

$$\int_V d^3V \vec{\nabla} \cdot \vec{E} = \oint_S \vec{E} \cdot \hat{n} d^2S \quad ??$$

$\vec{\nabla} \cdot \vec{E} \Rightarrow$  except at  $r=0$

(4)

Dirac  $\delta$ -function:

§ 13.1.3

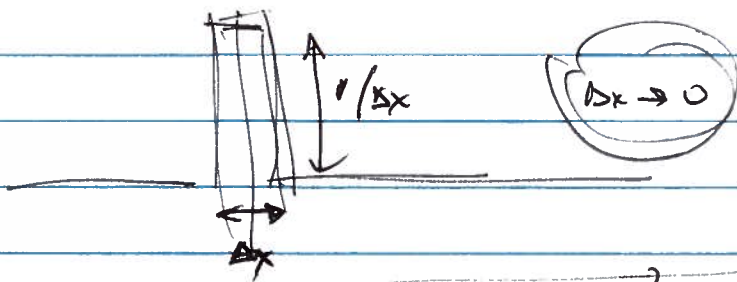
idealization .  $\delta(x) = \begin{cases} 0 & x \neq 0, \\ \infty & x = 0, \end{cases}$  (13.11)

such that  $\int_a^b dx \delta(x) = 1$   $\left\{ \begin{array}{l} a < 0 \\ b > 0 \end{array} \right.$  (13.12)  
(as small as you like).

$\Rightarrow \int dx f(x) \delta(x) = f(0)$

Can't really do that .  $\rightarrow$

limit of something  $\left\{ \begin{array}{l} \text{taller \& taller} \\ \text{narrower \& narrower} \end{array} \right.$



Nice .  $\left| \frac{1}{\sqrt{2\pi} \Delta x} e^{-\frac{1}{2} \frac{x^2}{(\Delta x)^2}} \right.$  Gaussian .  
(smooth, integrable)

$\Delta x \rightarrow 0$



(5)

Properties

$$[\delta(x)] = [x]^{-1}$$

$$[\delta(tx)] = [t]^{-1}$$

$$\int dx f(x) \delta(x-a) = ?$$

$$\begin{aligned} x' &= x-a \\ x &= x'+a \\ dx &= dx' \end{aligned}$$

$$= \int dx' f(x'+a) \delta(x') = f(0+a)$$

$$\boxed{\int dx f(x) \delta(x-a) = f(a)} \quad (13.12)$$

(Sometimes taken as defining property)

$$\int dx f(x) \delta(ax) = \int \frac{dx'}{|a|} f\left(\frac{x'}{a}\right) \delta(x') = \frac{1}{|a|} f(0)$$

$$x' = ax$$

$$x = \frac{x'}{a}$$

$$\boxed{\delta(ax) = \frac{1}{|a|} \delta(x)} \quad (13.16)$$

$$\textcircled{a = -1}$$

$$\boxed{\delta(-x) = \delta(x)}$$

even function  
(13.15)

$$\int_a^b dx f(x) \delta'(x) = \left[ f(x) \delta(x) \right]_a^b - \int dx f'(x) \delta(x)$$

$$\boxed{\int dx f(x) \delta'(x) = -f'(0)}$$

$$\boxed{\delta'(-x) = -\delta'(x)}$$

$$\underline{x \delta(x) = ?}$$

$$\int dx f(x) x \delta(x) = (x f(x)) \Big|_{x=0} = 0.$$

$$\boxed{x \delta(x) \stackrel{!}{=} 0}$$

(13.17)

$$\int dx f(x) \delta(h(x))$$

$$\text{let } x' = h(x)$$

$$dx' = h'(x) dx$$

$$= \int \frac{dx'}{|h'(x)|} f(h^{-1}(x')) \delta(x')$$

$$\underline{h(x) = 0 \text{ at } x = x_0.}$$

$$\rightarrow \frac{1}{|h'(x_0)|} f(x_0)$$

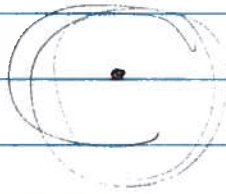
$$\rightarrow \sum_i \frac{1}{|h'(x_i)|} f(x_i)$$

$$\boxed{\delta(h(x)) = \sum_i \frac{1}{|h'(x_i)|} \delta(x - x_i)}$$

$$\text{near } x = x_i \quad h \approx h(x_i) + h'(x_i)(x - x_i) + \dots$$

$$\overset{(3)}{\delta(\vec{r})} = \delta(x) \delta(y) \delta(z)$$

Point charge



$$\int \vec{E} \cdot \hat{n} d^3a = 4\pi r^2 \cdot E = Q/\epsilon_0$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \hat{r}$$

$$\begin{aligned} \vec{\nabla} \cdot \vec{E} &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 E_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta E_\theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (\sin \theta E_\phi) \\ &= \frac{1}{r^2} \frac{\partial}{\partial r} \left( \frac{Q}{4\pi\epsilon_0} \right) = 0 \end{aligned}$$

Flux  $\neq 0$

divergence  $= 0$

$\delta$ -function