

Solutions to Asmt #2

(1a) * $\delta [q] = \int_{t_1}^{t_2} L(q(t'), \dot{q}(t'), \ddot{q}(t'), t) dt'$

* $\frac{\delta q}{\delta q(t)} = \int_{t_1}^{t_2} \left\{ \frac{\partial L}{\partial q} \delta(t-t) + \frac{\partial L}{\partial \dot{q}} \delta'(t-t) + \frac{\partial L}{\partial \ddot{q}} \delta''(t-t) \right\} = \left(\frac{\partial L}{\partial q} \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) + \frac{d^2}{dt^2} \left(\frac{\partial L}{\partial \ddot{q}} \right) \right) = 0$

(1b) * $\frac{dE}{dt} = \dot{q} \left[\frac{\partial L}{\partial q} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} \right] + \dot{q} \left[\frac{d}{dt} \frac{\partial L}{\partial \dot{q}} - \frac{d^2}{dt^2} \frac{\partial L}{\partial \ddot{q}} \right] + \ddot{q} \frac{\partial L}{\partial \ddot{q}} + \dot{q} \frac{d}{dt} \frac{\partial L}{\partial \ddot{q}} - \frac{\partial L}{\partial t} \dot{q} - \frac{\partial L}{\partial \dot{q}} \ddot{q} - \frac{\partial L}{\partial \ddot{q}} \ddot{q}$
 $= \dot{q} \left[-\frac{\partial L}{\partial q} + \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} - \frac{d^2}{dt^2} \frac{\partial L}{\partial \ddot{q}} \right] = 0 \quad QED$

(1c) * $L = L(q, \dot{q}, \ddot{q}) \rightarrow \frac{\partial L}{\partial q}, \frac{\partial L}{\partial \dot{q}}, \frac{\partial L}{\partial \ddot{q}} \delta - L$ each depend only upon q, \dot{q}, \ddot{q} , not \ddot{q}
 * $-\dot{q} \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = -\dot{q} \left[\frac{\partial^2 L}{\partial q \partial \dot{q}} \dot{q} + \frac{\partial^2 L}{\partial \dot{q} \partial \dot{q}} \dot{q} + \frac{\partial^2 L}{\partial \dot{q} \partial \ddot{q}} \ddot{q} \right]$
 $\therefore E$ is linear in \ddot{q}

* ~~Warning~~ if $\frac{\partial^2 L}{\partial \ddot{q}^2} \neq 0$ E can never be bounded below

* NB this is why Newton was right about $F=mg$

(2a) * $\dot{q}(t) = \sum_{n=0}^{\infty} \frac{n\pi}{T} a_n \sin\left(\frac{n\pi t}{T}\right) \rightarrow \dot{q}^2(t) = \sum_{k=0}^{\infty} \frac{k\pi}{T} a_k \sum_{l=0}^{\infty} \frac{l\pi}{T} a_l \sin\left(\frac{k\pi t}{T}\right) \sin\left(\frac{l\pi t}{T}\right)$

* $\sin(\alpha) \sin(\beta) = \frac{1}{2} \cos(\alpha - \beta) - \frac{1}{2} \cos(\alpha + \beta)$

$\rightarrow \sin\left(\frac{k\pi t}{T}\right) \sin\left(\frac{l\pi t}{T}\right) = \frac{d}{dt} \left\{ \frac{T}{2(k-l)\pi} \sin\left[\frac{(k-l)\pi t}{T}\right] - \frac{T}{2(k+l)\pi} \sin\left[\frac{(k+l)\pi t}{T}\right] \right\}$

* the integral of this $\int_0^T dt = \frac{T}{2} \delta_{kl} \rightarrow \int_0^T dt \frac{1}{2} m \dot{q}^2 = \frac{T}{4} m \sum_{k=0}^{\infty} \left(\frac{k\pi}{T}\right)^2 a_k^2$

* $\cos(\alpha) \cos(\beta) = \frac{1}{2} \cos(\alpha - \beta) + \frac{1}{2} \cos(\alpha + \beta)$

$\rightarrow \int_0^T dt \cos\left(\frac{k\pi t}{T}\right) \cos\left(\frac{l\pi t}{T}\right) = \frac{T}{2} \delta_{kl} \rightarrow -\frac{1}{2} k \int_0^T dt \dot{q}^2 = -\frac{T}{4} k \sum_{k=0}^{\infty} a_k^2$

$\therefore \delta [q] = \frac{T}{4} \sum_{n=0}^{\infty} a_n^2 \left[m \left(\frac{n\pi}{T}\right)^2 - k \right]$

(2b) $\frac{\partial \delta}{\partial a_n} = \frac{T}{2} \left[m \left(\frac{n\pi}{T}\right)^2 - k \right] a_n = 0$

(2c) * $q \frac{\delta \delta}{\delta q(t)} = -m \ddot{q}(t) - k q(t) = 0$

$\rightarrow \sum_{n=0}^{\infty} \left[m \left(\frac{n\pi}{T}\right)^2 - k \right] a_n \cos\left(\frac{n\pi t}{T}\right) = 0$

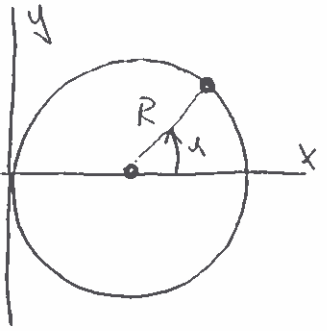
$\rightarrow \left[m \left(\frac{n\pi}{T}\right)^2 - k \right] a_n = 0 \quad (\text{same eqn!})$

Solutions to Asmt #2

3a) * $x(t) = R + R \cos(\omega t) \rightarrow \dot{x} = -R\dot{\alpha} \sin(\alpha)$

* $y(t) = 0 + R \sin(\omega t) \rightarrow \dot{y} = +R\dot{\alpha} \cos(\alpha)$

* $L_z = m(x\dot{y} - y\dot{x}) = mR^2\dot{\alpha}(1 + \cos(\alpha)) = 2mR^2\dot{\alpha} \cos^2(\alpha/2)$



3b) * $E = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2) + V(\sqrt{x^2 + y^2})$

* $\frac{1}{2}m(\dot{x}^2 + \dot{y}^2) = \frac{1}{2}mR^2\dot{\alpha}^2$

* $x^2 + y^2 = R^2[2 + 2\cos(\alpha)] = 4R^2\cos^2(\alpha/2) \rightarrow \sqrt{x^2 + y^2} = 2R\cos(\alpha/2)$

∴ $E = \frac{1}{2}mR^2\dot{\alpha}^2 + V(2R\cos(\alpha/2))$

3c) * $L = 2mR^2\dot{\alpha} \cos^2(\alpha/2) \rightarrow \dot{\alpha} = \frac{L}{2mR^2 \cos^2(\alpha/2)} = \frac{2L}{m} * \left[\frac{1}{2R \cos(\alpha/2)} \right]^2$

* $E = \frac{2R^2L^2}{m} \left[\frac{1}{2R \cos(\alpha/2)} \right]^4 + V(2R \cos(\alpha/2))$

* The only way for E to be constant is for $E = 0 \rightarrow V(r) = -\frac{2R^2L^2}{m} \frac{1}{r^4}$

3d) * $dt = \frac{d\alpha}{\dot{\alpha}} = \frac{mR^2}{L} (1 + \cos(\alpha)) d\alpha = \frac{mR^2}{L} d[\alpha + \sin(\alpha)]$

* $T = \frac{mR^2}{L} * 2\pi$