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Magnetostatics.

$$\begin{array}{ccc} \text{Electrostatics} & \rightarrow \vec{F}_g = q(\vec{E} + \vec{v} \times \vec{B}) & \text{Magnetostatics} \\ \vec{\nabla} \cdot \vec{E} = \frac{1}{\epsilon_0} \rho & \text{(Gauss's Law)} & \vec{\nabla} \cdot \vec{B} = 0 \quad (?) \\ \vec{\nabla} \times \vec{E} = 0 & (?) & \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \quad \text{(Ampere's Law)} \end{array}$$

↓ ↓ Maxwell's Eq for static case ↓ ↓

Determine \vec{E} with $\vec{E} \rightarrow 0$ as $r \rightarrow \infty$ from q . Determine \vec{B} with $\vec{B} \rightarrow 0$ as $r \rightarrow \infty$ from \vec{J} .

EX Consider a copper wire of radius $1 \text{ mm} = 10^{-3} \text{ m}$.
Each copper atom provides one free electron.

(i) What is the electron density of Cu?

Atomic mass of Cu = 64 gm/mole = $64 \times 10^{-3} \text{ kg/mole}$

$N_A = 6 \times 10^{23} / \text{mole}$

ρ_M : mass density of Cu = 9 gm/cm³ = $9 \times 10^3 \text{ kg/m}^3$

ρ_e : electron density of Cu.

$$\rho_e = \frac{(6 \times 10^{23})}{64 \times 10^{-3}} \cdot 9 \times 10^3 \approx 10^{29}$$

\therefore Charge density $\rho_q = e \times \rho_e = (1.6 \times 10^{-19})(10^{29}) \approx \underline{2 \times 10^{10} \text{ C/m}^3}$.

(ii). When 1 A of current is flowing in the wire, what is the drift speed of electrons?

$$J = \frac{I}{\pi a^2} = \frac{1}{\pi (10^{-3})^2} = \frac{1}{\pi} 10^6 \approx 3 \times 10^5 \text{ (A/m}^2\text{)}$$

$$= \rho_q v$$

$$\therefore v = \frac{J}{\rho_q} = \frac{3 \times 10^5}{2 \times 10^{10}} \approx 1.5 \times 10^{-5} \text{ (m/s)} = 1.5 \times 10^{-3} \text{ cm/s}$$

▷ Vector Potential \vec{A}

$$\vec{\nabla} \times \vec{E} = 0 \Rightarrow \vec{E} = -\vec{\nabla} V(\vec{r}) \quad \text{--- ①}$$

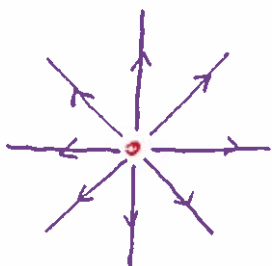
Similarly

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \vec{B} = \vec{\nabla} \times \vec{f}(\vec{r}) \quad \text{--- ②} \quad \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$$

"vector potential"

Now we can set up a differential eq. for \vec{A} .

$$\begin{aligned} \vec{\nabla} \times \vec{B} &= \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) - (\vec{\nabla} \cdot \vec{\nabla}) \vec{A} = \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A} \\ &= \mu_0 \vec{J} \quad \text{--- ③} \end{aligned}$$



Source of $\vec{\nabla} \cdot \vec{A} \Rightarrow$ Charge



Source of $\vec{\nabla} \times \vec{A} \Rightarrow$ Current

In electrostatics, the electric potential possesses an ambiguity since $V(\vec{r}) \rightarrow V(\vec{r}) + \text{const}$ produces the same \vec{E} :

$$\vec{\nabla} V(\vec{r}) = \vec{\nabla} (V(\vec{r}) + \text{const})$$

Similarly, in magnetostatics, the vector potential can only be determined with a function $\vec{f}(\vec{r})$ which satisfies

$$\vec{\nabla} \times \vec{f}(\vec{r}) = 0 \quad \rightarrow \text{Gauge Invariance}$$

$$\therefore \vec{\nabla} \times \vec{A}(\vec{r}) = \vec{\nabla} \times (\vec{A} + \vec{f}) = \vec{B}$$

If $\vec{f}(\vec{r}) = \vec{\nabla} \lambda(\vec{r})$, then $\vec{\nabla} \times \vec{\nabla} \lambda(\vec{r}) = 0$.

This means we can choose a proper $\lambda(\vec{r})$ to make

$$\vec{\nabla} \cdot \vec{A} = 0 \quad \text{in eq ③ above.}$$

Let's say $\vec{\nabla} \cdot \vec{A}_0 \neq 0$. But replacing $\vec{A}_0 \rightarrow \vec{A}_0 + \vec{\nabla} \lambda$ is perfectly fine!

$$\vec{\nabla} \cdot \vec{A} = \vec{\nabla} \cdot (\vec{A}_0 + \vec{\nabla} \lambda) = \vec{\nabla} \cdot \vec{A}_0 + \nabla^2 \lambda = 0$$

$$\therefore \boxed{\nabla^2 \lambda = -\vec{\nabla} \cdot \vec{A}_0} \iff (\nabla^2 V = -\rho/\epsilon_0 : \text{Poisson eq.})$$

$$\therefore \lambda(\vec{r}) = -\frac{1}{4\pi} \int \frac{\vec{\nabla} \cdot \vec{A}_0}{r} d\tau'$$

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{r} d\tau'$$

if $\vec{\nabla} \cdot \vec{A}_0$ is localized!

However if $\vec{\nabla} \cdot \vec{A}_0$ is extended to infinity, then use a different method.

It is always possible to make $\vec{\nabla} \cdot \vec{A} = 0$ $\xRightarrow{\text{eg } \textcircled{2}}$ $\nabla^2 \vec{A} = -\mu_0 \vec{J}$

Vector Poisson eq.

$$\therefore \vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}')}{r} d\tau'$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{I} dl'}{r} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l}'}{r}$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{K}(\vec{r}') da'}{r}$$

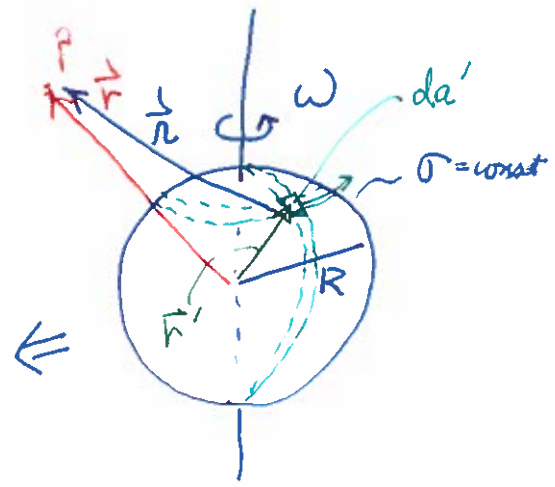
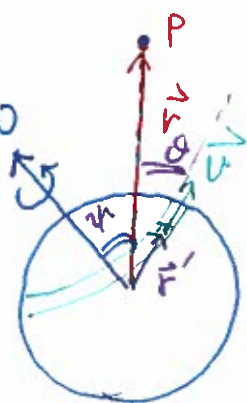
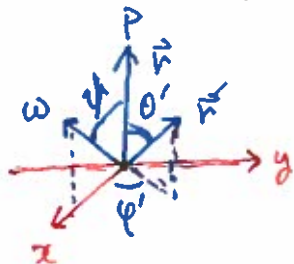
EX

$\vec{K} = \sigma \vec{v}$ and set $\vec{r} = z \hat{z}$

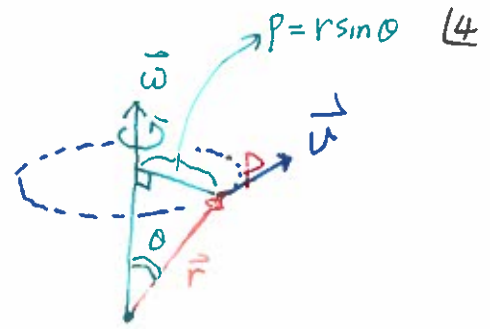
$$\vec{R} = \vec{r} - \vec{r}'$$

$$r = \sqrt{r'^2 + R^2 - 2Rr' \cos \theta'}$$

$$da' = R^2 \sin \theta' d\theta' d\phi'$$



Digression: Relation between $\vec{\omega}$ and \vec{v}



The radius of the circular path of P

$$\rho = r \sin \theta.$$

$$\therefore |\vec{v}| = \rho \dot{\varphi} = (r \sin \theta) \omega.$$

The direction is in $\hat{\varphi}$ and consequently in $\hat{\omega} \times \hat{r}$.

$$\text{Therefore } \vec{v} = \vec{\omega} \times \vec{r}.$$

In general if \hat{e} is a unit vector fixed in a rotating body.

$$\frac{d\hat{e}}{dt} = \hat{\omega} \times \hat{e}.$$

$$\vec{v} = \vec{\omega} \times \vec{r}' = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \omega \sin \psi & 0 & \omega \cos \psi \\ R \sin \theta' \cos \varphi' & R \sin \theta' \sin \varphi' & R \cos \theta' \end{vmatrix}$$

$$= R\omega \left[-\cos \psi \sin \theta' \sin \varphi' \hat{x} + (\cos \psi \sin \theta' \cos \varphi' - \sin \psi \cos \theta') \hat{y} + \sin \psi \sin \theta' \sin \varphi' \hat{z} \right]$$

Since $\int_0^{2\pi} \sin \varphi' d\varphi' = \int_0^{2\pi} \cos \varphi' d\varphi' = 0,$

the only surviving term when $\int da'$, is $-\sin \psi \cos \theta' \hat{y}$.

$$\begin{aligned} \therefore \vec{A}(\vec{r}) &= \frac{\mu_0}{4\pi} \int \frac{\vec{K}(\vec{r}')}{r} da' = \frac{\mu_0 \sigma(R\omega)}{4\pi} \int_0^{2\pi} d\varphi' \int_0^\pi d\theta' \frac{-\sin \psi \cos \theta' R^2 \sin \theta' d\theta'}{\sqrt{R^2 + r^2 - 2Rr \cos \theta'}} \hat{y} \\ &= -\frac{\mu_0 R^3 \omega \sigma}{2} \int_0^\pi d\theta' \frac{\sin \psi \cos \theta' \sin \theta' d\theta'}{\sqrt{R^2 + r^2 - 2Rr \cos \theta'}} \hat{y} \end{aligned}$$

We have done a similar integral in HW and class Prob. 2.7

$$\int_0^\pi \frac{\cos\theta' \sin\theta' d\theta'}{\sqrt{R^2+r^2-2Rr\cos\theta'}} = \int_{-1}^1 \frac{t dt}{\sqrt{R^2+r^2-2Rrt}} \quad \left(\begin{array}{l} \cos\theta' = t \\ -\sin\theta' d\theta' = dt \end{array} \right)$$

$$= - \frac{(R^2+r^2+Rrt)}{3R^2r^2} \sqrt{R^2+r^2-2Rrt} \Big|_{-1}^{+1}$$

$$= - \frac{1}{3R^2r^2} \left[(R^2+r^2+Rr)|R-r| - (R^2+r^2-Rr)(R+r) \right]$$

$$= \begin{cases} \frac{2r}{3R^2} & \text{for } r < R \text{ (inside)} \\ \frac{2R}{3r^2} & \text{for } r > R \text{ (outside)} \end{cases}$$

$$\therefore \vec{A}(\vec{r}) = \begin{cases} -\frac{\mu_0}{2} R^3 \omega \sigma \sin\psi \left(\frac{2r}{3R^2} \right) \hat{y} = \frac{\mu_0 R \omega \sigma}{3} r (\vec{\omega} \times \vec{r}) & (r < R) \\ -\frac{\mu_0}{2} R^3 \omega \sigma \sin\psi \left(\frac{2R}{3r^2} \right) \hat{y} = \frac{\mu_0 R^4 \omega \sigma}{r^2} (\vec{\omega} \times \vec{r}) & (r > R) \end{cases}$$

Go back to the original coordinates.

$$\vec{A}(r, \theta, \varphi) = \begin{cases} \frac{\mu_0 R \omega \sigma}{3} (\vec{\omega} \times \vec{r}) = \frac{\mu_0 R \omega \sigma}{3} r \sin\theta \hat{\varphi} \\ \frac{\mu_0 R^4 \omega \sigma}{3r^2} (\vec{\omega} \times \vec{r}) = \frac{\mu_0 R^4 \omega \sigma}{3} \frac{\sin\theta}{r^2} \hat{\varphi} \end{cases}$$

then, $\vec{B} = \nabla \times \vec{A}$

EX \vec{A} of an infinite solenoid.

Consider a line integral on a closed loop of \vec{A}

$$\oint \vec{A} \cdot d\vec{c} = \int_S (\nabla \times \vec{A}) \cdot d\vec{a} = \int_S \vec{B} \cdot d\vec{a} = \Phi_m$$

Stokes thm Magnetic flux

$$\Phi_e = \int \vec{E} \cdot d\vec{a}$$

$$\therefore \oint \vec{A} \cdot d\vec{\ell} = \Phi_m$$

The above eq. has the same mathematical structure as Ampere's Law.

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I_{en}$$

For a straight current $I = I \hat{z}$, we know that

$$\vec{B} = \frac{\mu_0 I}{2\pi s} \hat{\varphi}$$

Similarly, for a Φ_m in from $\vec{B} = B_0 \hat{z}$,

$$\vec{A} = \frac{\Phi_m}{2\pi s} \hat{\varphi} \quad \text{for } s \text{ outside of confined flux.}$$

The magnetic field inside an infinite solenoid

$$\vec{B} = \mu_0 n I \hat{z} \quad (\text{uniform field}).$$

For a closed loop inside the solenoid ($s < R$).

$$\oint \vec{A} \cdot d\vec{\ell} = 2\pi s A_\varphi = \pi s^2 (\mu_0 n I)$$

$$\therefore \vec{A} = \frac{\mu_0 n I}{2} s \hat{\varphi}$$

For $s > R$

$$\oint \vec{A} \cdot d\vec{\ell} = 2\pi s A_\varphi = \pi R^2 (\mu_0 n I)$$

$$\vec{A} = \frac{\mu_0 n I R^2}{s} \hat{\varphi}$$



HW 5.23 - 5.27.