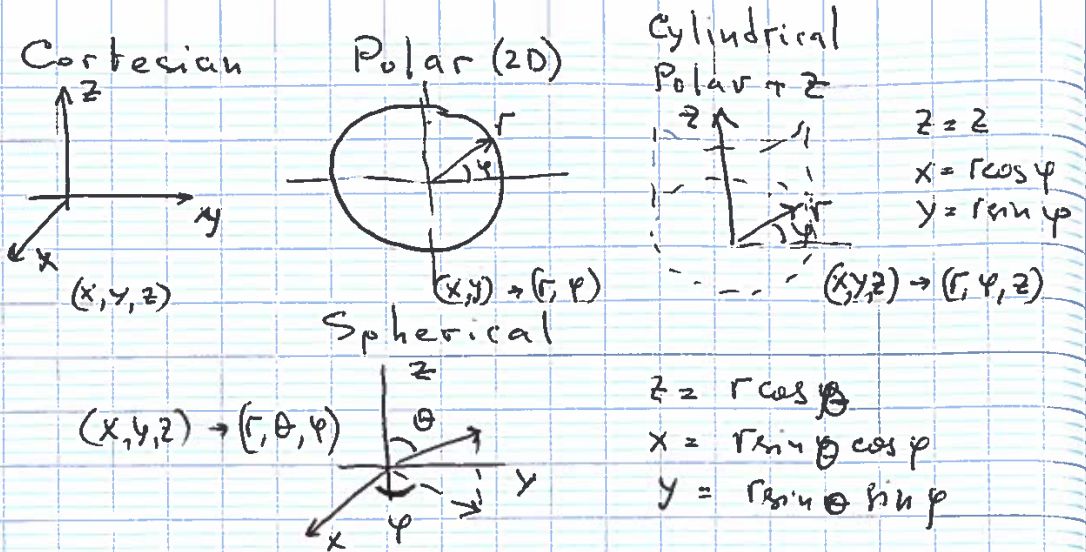
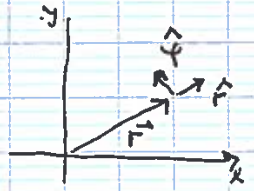


L5



- 2D Polar coordinates



$$\vec{F} = F_r \hat{r} + F_\varphi \hat{\varphi}$$

$$\text{Line element: } d\vec{s} = dr \hat{r} + r d\varphi \hat{\varphi}$$

$$d\vec{s} = \vec{r}(t+\Delta t) - \vec{r}(t)$$

Velocity  $\vec{v} = \frac{d\vec{r}}{dt} = \dot{\vec{r}} = \left(\frac{ds}{dt}\right)_{dt \rightarrow 0} = \dot{r} \hat{r} + r \dot{\varphi} \hat{\varphi}$

acceleration  $\vec{a} = \ddot{\vec{r}} = \frac{d\dot{\vec{r}}}{dt} = (\ddot{r} - r\dot{\varphi}^2) \hat{r} + (r\ddot{\varphi} + 2\dot{r}\dot{\varphi}) \hat{\varphi}$

used:  $\frac{d\hat{r}}{dt} = \dot{\varphi} \hat{\varphi}$      $\frac{d\hat{\varphi}}{dt} = -\dot{\varphi} \hat{r}$  (see text book) Fig 1.13

- Newton's 2<sup>nd</sup> Law in polar coordinate

$$\vec{F} = m \vec{a} \rightarrow \begin{aligned} F_r &= m(\ddot{r} - r\dot{\varphi}^2) \quad \leftarrow \text{centripetal} \\ F_\varphi &= m(r\ddot{\varphi} + 2\dot{r}\dot{\varphi}) \quad \leftarrow \text{Coriolis} \\ F_z &= m\ddot{z} \quad (\text{cylindrical}) \end{aligned}$$

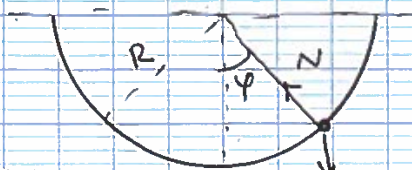
$r = \text{const}$   
 $z = \text{const.}$

$$F_r = -4r\dot{\varphi}^2 = -r\omega^2 m$$

$$F_\varphi = m r \dot{\omega}$$

L5

## Example 1.2 An Oscillating Skateboard.



$$r = R$$

$$F_r = -mR\dot{\varphi}^2$$

$$F_\varphi = mR\ddot{\varphi}$$

$$w = mg$$

$$F_r = mg \cos \varphi - N$$

$$F_\varphi = -mg \sin \varphi$$

$$-mg \sin \varphi = mR\ddot{\varphi}$$

$$\ddot{\varphi} = -\frac{g}{R} \sin \varphi$$

$$\ddot{\varphi} = -\frac{g}{R} \varphi$$

$$\varphi \ll 1.$$

define  $\omega = \sqrt{g/R}$   $\ddot{\varphi} = -\omega^2 \varphi$

solutions:  $\varphi_1(t) = A \sin \omega t$

$\varphi_2(t) = B \cos \omega t$

$\varphi(t) = \varphi_1(t) + \varphi_2(t)$  - general solution.

- consider initial conditions.

- period of oscillations:  $T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{R}{g}}$